Online Machine Learning

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Definition



- **Online machine learning** (OML) is a method of machine learning in which:
 - data becomes available in a sequential order
 - is used to update our best predictor for future data at each step,

as **opposed to batch learning** techniques which generate the best predictor by learning on the entire training data set at once

Difference to standard approach

- Online prediction refers to the problem of prediction in the online protocol (sequential prediction problems):
 - Nature outputs some side information
 - Predictor outputs a prediction
 - Nature outputs an observation
 - The cycle is repeated
- Difference to usual supervised learning:
 - Test and Train datasets are the same but the distinguish between train and test is through time



Motivation example

- A problem:
 - What is papaya?
 - How to find good papaya?



Motivation example

- A problem:
 - What is papaya?
 - How to find good papaya?
 - Buy papaya and let's try to predict if it is ok.





Motivation



- It is computationally infeasible to train over the entire dataset
 - So should train by **mini-batches** (or one-by-one)
- It is used in situations where it is necessary for the algorithm to dynamically adapt to new patterns in the data
 - Data changes too fast decrease lag
 - Fast tuning to important data trends

How to solve it?

- Recursive adaptive algorithms (Robbins and Monro 1951)
- Stochastic approximation (Kushner and Clark, 1978)
- Adaptive filtering (Haykin 2002, 2010)



Model types

- Statistical models
 - Data samples are usually assumed to be i.i.d.
 - Algorithm just has a limited access to the data
- Adversarial models
 - They are looking at the learning problem as a game between two players (the learner vs the data generator)
 - The goal is to minimize losses regardless of the move played by the other player





I. Statistical online models

- Gradient descent
- Kalman filtering
- Kernel model
- SVM
- Folding-in

1. Batch gradient descent

$$w_{t+1} = w_t - \gamma_t \nabla_w \hat{J}_L(w_t) = w_t - \gamma_t \frac{1}{L} \sum_{i=1}^L \nabla_w Q(x_i, w_t)$$

- We can speed up convergence by replacing $\gamma_{\it t}$ by positive matrix
- We should **save all points** from training dataset
- Compute average gradient for all points



Online gradient descent

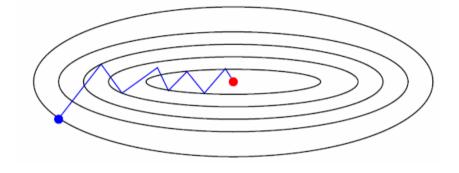
• We don't do averaging

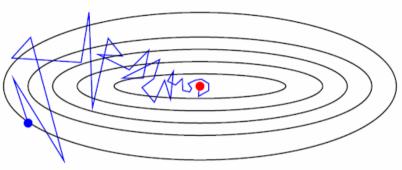
$$w_{t+1} = w_t - \gamma_t \nabla_w Q(x_t, w_t)$$

- Use just one point one at a time
- We **hope** that random selection will not perturbate the average behavior of the algorithm

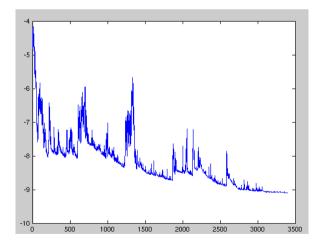


Online gradient descent





- So we see weird behavior
- Is there a convergence?



Online gradient descent



- The main question: is there a convergence?
- Theory: Yes!
 - When the learning rate decreases with an appropriate rate
 - We will get global minimum if objective function is convex, otherwise almost surely will get local minimum

Gradient descent optimizations

- There is a couple of GD optimizations:
 - Momentum (Sutton, R. S. 1986)
 - Nesterov accelerated gradient (Nesterov, Y. 1983)
 - AdaGrad (Duchi, J., Hazan, E., & Singer, Y. 2011)
 - Adadelta (extension of AdaGrad)
 - Stochastic average gradient (Le Roux, Schmidt, and Bach, 2012)



AdaGrad

- SGD with per-parameter learning rate
 - Large for more sparse parameters

$$g_t = \nabla_w Q(x_t, w_t)$$

$$G_{t,jj} = \sum_{k=1}^{l} g_{k,j}^{2}$$

 $w_{t+1} = w_t - \gamma \cdot diag \left(G_t + e\right)^{-1/2} \circ g_j$

- Useful for sparse applications (for example NLP and image recognition)
 - Used in Google
 - Used for Glove model



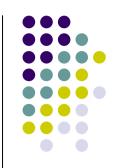
2. Kalman filtering

- Recursive least squares filter
- Quasi-Newton algorithm

$$K_{t} = H_{t-1}^{-1}$$

$$K_{t+1} = K_{t} - \frac{(K_{t}x_{t})(K_{t}x_{t})}{1 + x_{t}^{T}K_{t}x_{t}}^{T}$$

$$w_{t+1} = w_{t} - K_{t+1}(y_{t} - w_{t}^{T}x_{t})^{T}x_{t}$$





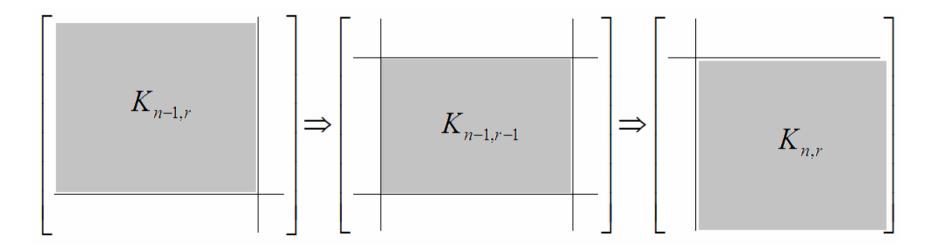
• Batch regime:

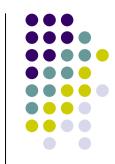
$$\alpha = K(\lambda)^{-1}Y = (K + \lambda I)^{-1}Y$$

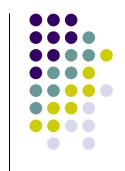
$$K_{i,j} = \kappa(x_i, x_j), \quad i, j = 1, r$$

- The main problem: how to update inverse matrix
- It is possible to do in 2 stages:

$$\mathbf{K}_{n-1,r}^{-1}(\lambda) \to \mathbf{K}_{n-1,r-1}^{-1}(\lambda) \to \mathbf{K}_{n,r}^{-1}(\lambda)$$







Т

Online Kernel models

$$\alpha_{n} = (K_{n-1,r}(\lambda))^{-1} (\lambda^{-1} \alpha_{n-1} + Y_{n-1,r})$$

$$K_{n-1,r-1}^{-1} = R_{r} K_{n-1,r}^{-1} R_{r}^{T} - (e_{1}^{T} K_{n-1,r}^{-1} e_{1})^{-1} R_{r} K_{n-1,r}^{-1} e_{1} e_{1}^{T} K_{n-1,r}^{-1} R_{r}^{T}$$

$$K_{n,r}^{-1}(\lambda) = \begin{pmatrix} A & B \\ C & \delta_{n}^{-1} \end{pmatrix}$$

$$A = K_{n-1,r-1}^{-1} + \delta_{n}^{-1} \cdot K_{n-1,r-1}^{-1} \cdot k_{n-1,r-1} (x_{n}) \cdot k_{n-1,r-1}^{T} (x_{n$$

$$B = -\delta_n^{-1} K_{n-1,r-1}^{-1} \cdot k_{n-1,r-1}(x_n)$$

$$C = B^{T} = -\delta_n^{-1} k_{n-1,r-1}^{T}(x_n) \cdot K_{n-1,r-1}^{-1}$$

$$\delta_n = \lambda^{-1} + k_{n,n} - k_{n-1,r-1}^{T}(x_n) \cdot K_{n-1,r-1}^{-1} \cdot k_{n-1,r-1}(x_n)$$

$$R_r = (0_r; I_{r-1}) \qquad e_1 = (1 \quad 0 \quad \dots \quad 0)^{T}$$

$$k_{n-1,r-1}^{T}(x_n) = (\kappa(x_n, x_{n-r+1}) \dots \kappa(x_n, x_{n-1}))$$

$$k_{n,n} = \kappa(x_n, x_n)$$



- The issue is a complexity
- Accumulate new observations in Gram matrix
- Control complexity of Gram matrix:
 - Sparsification
 - Prunning



• Approximate Linear Dependency (Engel 2004)

$$\delta_{t} = \min_{a} \left\| \sum_{j=1}^{m_{t-1}} a_{j} \phi(\widetilde{x}_{j}) - \phi(x_{t}) \right\|^{2} \leq v$$
$$\delta_{t} = \min_{a} \left\{ a^{T} \widetilde{K}_{t-1} a - 2a^{T} \widetilde{K}_{t-1}(x_{t}) + k_{tt} \right\}$$

• Novelty criterion (Haykin 2010)



 More about kernels and recursive models: "Kernel Adaptive Filtering A Comprehensive Introduction (Adaptive and Learning Systems for Signal Processing, Communications and Control Series)" by Haykin

4. Online SVMs

- The most famous is LASVM algorithms (Léon Bottou 2005-2011)
- There is a package for R: <u>https://cran.r-</u> project.org/web/packages/lasvmR/index.html
- Uses 2 steps: PROCESS & REPROCESS
- In general add and delete support vectors



5. Folding-in

• SVD decomposition for recommender systems

$$SVD(A) = U \times S \times V^{T}$$
$$A \approx U_{k} \times S_{k} \times V_{k}^{T}$$
$$P_{i,j} = \overline{r_{i}} + \left(U_{k} \sqrt{S_{k}}^{T}(i)\right) \cdot \left(\sqrt{S_{k}}^{T} V_{k}(j)\right)$$

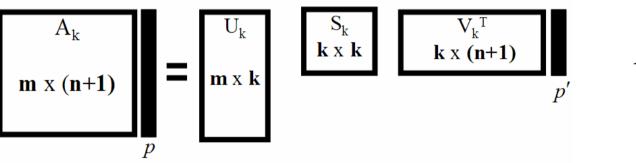
- Challenge: building SVD is time consuming
- How to add new product, new customer?



Incremental Singular Value Decomposition

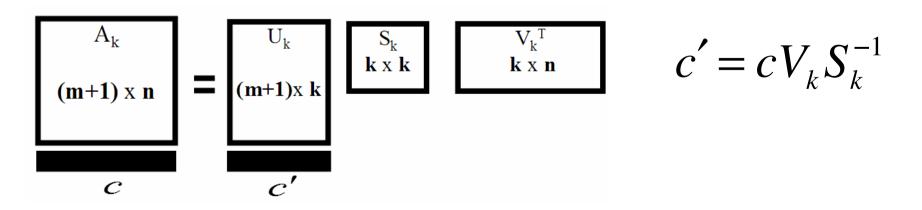


1) New product p (mx1)



 $p' = p^T U_k S_k^{-1}$

2) New customer c (1xn)





II. Adversarial models

• Definition:

- Player chooses W_t
- Adversary chooses $l_{t}(w)$
- Player suffers loss $l_t(w_t)$
- Need to minimize cumulative loss
- Some standard algorithms:
 - Follow the leader (FTL)
 - Follow the regularised leader (FTRL)

Adversarial models



- We will not look at this models, but they have several advantages:
 - In contrast to statistical machine learning (stochastic), adversarial algorithms don't make stochastic assumptions about the data they observe, and even handle situations where the data is generated by a malicious adversary
 - So no i.i.d. assumption!

Pros and Cons of Online ML algorithms

- Online algorithms are
 - Often much faster
 - More memory-efficient
 - Can adapt to the best predictor changing over time
 - Hard to maintain in production
 - Hard to evaluate
 - Have problems with convergence



Applications



- Online Machine Learning can be used for:
 - Computer vision
 - Recommender systems
 - Predicting stock market trends
 - Deciding which ads to present on a web page
 - IoT applications
- Put here your application...

Useful Links



- <u>http://sebastianruder.com/optimizing-gradient-</u> <u>descent/index.html</u>
- Kernel Adaptive Filtering A Comprehensive Introduction (Haykin 2010)
- The Kernel Recursive Least Squares Algorithm (Engel 2003)
- Foundations of Machine Learning (M. Mohri, A. Rostamizadeh, and A. Talwalkar 2012)



Thank you!

Questions?

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